

# CALIOP Uncertainty Estimates

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# Aerosol Layer Product

**Table 34: Lidar 5 km Layer Descriptor Record: Aerosols**

Parameter	Data Type	Units	Nominal Range	Elem/ Rec	Bytes
Feature_Optical_Depth_532	Float_32	NoUnits	0.0...3.0	8	32
Feature_Optical_Depth_Uncertainty_532	Float_32	NoUnits	0.0...TBD	8	32
Feature_Optical_Depth_1064	Float_32	NoUnits	0.0...3.0	8	32
Feature_Optical_Depth_Uncertainty_1064	Float_32	NoUnits	0.0...TBD	8	32
ExtinctionQC_532	UInt_16	NoUnits	0...65,535	8	16
ExtinctionQC_1064	UInt_16	NoUnits	0...65,535	8	16
CAD_Score	Int_8	NoUnits	-101...105	8	8

# Column Properties

**Table 33: Lidar 5 km Column Descriptor Record: Aerosols**

Parameter	Data Type	Units	Nominal Range	Elem/ Rec	Bytes
Column Optical Depth Aerosols 532	Float_32	NoUnits	0.0...3.0 <sup>M</sup>	1	4
Column Optical Depth Aerosols Uncertainty 532	Float_32	NoUnits	0.0...99.99	1	4
Column Optical Depth Stratospheric 532	Float_32	NoUnits	0.0...3.0 <sup>M</sup>	1	4
Column Optical Depth Stratospheric Uncertainty 532	Float_32	NoUnits	0.0...99.99	1	4
Column Optical Depth Aerosols 1064	Float_32	NoUnits	0.0...3.0 <sup>M</sup>	1	4
Column Optical Depth Aerosols Uncertainty 1064	Float_32	NoUnits	0.0...99.99	1	4

# Aerosol Profile Product

**Table 37: Lidar 5 km Aerosol Profile Record**

Parameter	Data Type	Units	Nominal Range	Elem/ Rec	Bytes
Extinction_Coefficient_532	Float_32	km <sup>-1</sup>	0.0...1.25	399	1,596
Extinction_Coefficient_Uncertainty_532	Float_32	km <sup>-1</sup>	0.0...99.99	399	1,596
Aerosol_Multiple_Scattering_Profile_532	Float_32	NoUnits	1.0	399	1,596
Backscatter_Coefficient_1064	Float_32	sr <sup>-1</sup> km <sup>-1</sup>	0.0...0.03	399	1,596
Backscatter_Coefficient_Uncertainty_1064	Float_32	sr <sup>-1</sup> km <sup>-1</sup>	0.0...99.99	399	1,596
Extinction_Coefficient_1064	Float_32	km <sup>-1</sup>	0.0...1.0	399	1,596
Extinction_Coefficient_Uncertainty_1064	Float_32	km <sup>-1</sup>	0.0...99.99	399	1,596

- **There are two retrieval algorithms used in the standard products**
  - **Constrained retrieval**
    - Lidar ratio derived from layer transmittance measurement and used as constraint on the extinction retrieval
  - **Unconstrained retrieval**
    - Lidar ratio needed by the extinction retrieval is estimated by an aerosol typing algorithm
    - Daytime aerosol retrievals are almost always unconstrained

**The extinction retrieval solves for the particulate backscatter coefficient,  $\beta_p(r)$ :**

$$\beta_P(r) = \beta'_N(r) / (T_M^2(r_N, r) T_P^2(r_N, r)) - \beta_M(r)$$

**Which is a simple re-formulation of the lidar equation:**

$$\beta'_N(r) = \beta'(0, r) / C_N(r_N) = [\beta_M(r) + \beta_P(r)] T_M^2(r_N, r) T_P^2(r_N, r)$$

**These equations are the basis for an error propagation analysis of the estimated error sources**

**The Retrieval of Profiles of Particulate Extinction from *Cloud–Aerosol Lidar and Infrared Pathfinder Satellite Observations (CALIPSO)* Data: Uncertainty and Error Sensitivity Analyses**

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# Error Estimation

## **Sources of error considered**

- Calibration
- Aerosol lidar ratio
- SNR

## **Sources of error not considered**

- Misclassification of aerosol and cloud
- Misclassification of aerosol type
- Failure to detect layers

## **Standard propagation of errors techniques are used to estimate:**

- Aerosol extinction at each level
- AOD of each aerosol layer
- Column AOD



# Error Estimates

Error in extinction due to an error in calibration:

$$\varepsilon[\sigma_P(r)] = S_P \beta_T(r) \left[ \alpha \frac{T_P^2(0, r)}{\hat{T}_P^2(0, r)} - 1 \right], \quad (30)$$

Error in optical depth :

$$\begin{aligned} \varepsilon[\tau_P(0, r)] &= -0.5 \ln \left[ \frac{\hat{T}_P^2(0, r)}{T_P^2(0, r)} \right] \\ &= -0.5 \ln \left\{ 1 + \frac{\varepsilon[T_P^2(0, r)]}{T_P^2(0, r)} \right\}. \end{aligned} \quad (31)$$

Error in extinction due to an error in lidar ratio:

$$\varepsilon[\sigma_P(r)] = (\psi - 1) S_P \beta_P(r) + \psi S_P \beta_T(r) \left[ \frac{T_P^2(0, r)}{\hat{T}_P^2(0, r)} - 1 \right], \quad (39)$$